Automation Technology 1

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Course Number	01005133	Subject Category Cradit Type and	Compulsory (M	}
Department	Mechatronics	Number of Credits Student Category	1 Year 5	
Period of Study Required Materials	Semester 1	Classes per Week	1	
Course Objective	The lease cooke level have			1
To introduce the fundamentals of auto related sensors and controllers linclude the end of this course, the students an conveyor systems.	mation technology with a foc. ng PLCI, and the application o a able to explain the sensors, o	is on conveyor systems, f CAD tools, QR codes, controllers, and related t	their design principles, and motors in the field, At technologies, and design the	
Evaluation (Rubric)	Ideal Level of Achievement (Very Good)	Standard Level of Achievement (Good)	Unacceptable Level of Achievement (Fail	
can explain the characteristics of conveyor systems and the basic components and operations.	can explain the characteristics of conveyor systems and the basic components and operations in detail and precisely.	can explain the characteristics of conveyor systems and the basic components and operations.	can not explain the characteristics of conveyor systems and the basic components and operations.	-
can identify the role of sensors in conveyor systems and automation, and demonstrate knowledge of sensor types, their functions, and applications.	can identify the role of sensors in conveyor systems and automation, and demonstrate knowledge of sensor types, their functions, and apolications, in detail and precisely.	can identify the role of sensors in conveyor systems and automation, and demonstrate knowledge of sensor types, their functions, and applications,	can not identify the role of sensors in conveyor systems and automation, and demonstrate knowledge of sensor boes, their functions, and applications.	
can use CAD tools to design and model converor systems and components and aimulate the mechanics of the systems.	can use CAD tools to design and model conveyor systems and components precisely and simulate the mechanics of the systems correctly.	can use CAD tools to design and model conveyor systems and components and simulate the mechanics of the systems.	Can use CAD tools to design and model converor systems and components and simulate the mechanics of the systems.	
M(1) Ability to design, propose and d	Relationship with Learnin develop robotio/ mechatron	g Outcomes to systems to solve ap	eolfio problems	1
(2) Ability to design, propose and develop electrical and electronic systems for robotics/ mechatronic systems				
M(3) Ability to design, propose and	develop mechanical solution	s/ systems for robotic	/ mechatronic systems	
Teaching Method]
Outline: Class Format:	Lecture and Practice Lecture. Practice and Homework Assignments Students are meruined to ack and and are attract of felicentian			-
Course Plan	Students are required to ask any questions at		ar sundent sennearning	1
Semester 1	Contents and Met	hod of Course	Goals	Related MCC
1st week	Guidance of Automation Technology		Explaining what "Automation Technology" is.	
2nd week	Review of Mechanics		Calculating bending problems and drawing SFD and BMD.	V-A 3 65 V-A 3 66 V-A 3 67 V-A 3 68 V-A 3 68 V-A 3 69 V-A 3 70 V-A 3 51
3rd week	Chute conveyor		Explaining the mechanics of the chute conveyor	V-A 3 52 V-A 3 53 V-A 3 54
4th week	Designing chute conveyor		Can design the chute conveyor	V-A 3 51 V-A 3 52 V-A 3 53 V-A 3 54
5th week	Belt conveyor and roller conveyor		Explaining the differences between belt and roller conveyors	V-A 3 51 V-A 3 52 V-A 3 53 V-A 3 54
6th week	Designing belt conveyor		Can design belt conveyor	V-A 3 51 V-A 3 52 V-A 3 53 V-A 3 54
7th week	Designing roller conveyor		Can design roller conveyor	V-A 3 51 V-A 3 52 V-A 3 53 V-A 3 54
8th week	Mid-term examination			
9th week	Controllers and sensors in conveyor systems		Can identify the role of sensors and controllers IPLCI in conveyor systems and automation.	W-C 1 11 W-C 1 12 W-C 1 13 W-C 1 14 W-C 1 15
10th week	Designing conveyor systems by using CAD (1)		Can design conveyor systems and their components using CAD	V-A 1 8 V-A 1 9 V-A 1 10
11th week	Designing conveyor systems by using CAD (2)		Can design conveyor systems and their components using CAD	V-A 1 8 V-A 1 9 V-A 1 10
12th week	Soring systems used in logistic systems		Can explain sorting systems in conveyor systems and applications	V-A 2 11 V-A 2 12 V-A 2 13
13th week	Mechanics and Equipments in logistic systems		Group work for designing logistic system	V-A 2 11 V-A 2 12 V-A 2 13
14th week	Design logistic system (1)		Group work for designing logistic system	V-A 1 8 V-A 2 11 V-A 2 12 V-A 2 13
15th week	Design logistic system (2)		Group work for designing logistic system	V-A 1 8 V-A 2 11 V-A 2 12 V-A 2 13
16th week	Design logistic system (3)		Group work for designing logistic system	V-A 1 8 V-A 2 11 V-A 2 12 V-A 2 13
17th week	Presentation of designed logistic system		Group work for designing logistic system	
18th week	Preparation for final examination			
19th week	Final examination			
20th week	wrap-up			
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Basic Ability Technical Ability	40 0	wulz	mutual Brakastone between students	20 20
Interdisciplinary Ability	1	1		20