## Lab work 3 for Robotics

Course Number	01005123 Subject Catego		Compulsory (M	
Class Format	Experiment / Practical trainin	Credit Type and Number of Credits	1.5	
Department	Mechatronics	Student Category	Year 2	
Period of Study	Semester 1	Classes per Week	3	
Required Materials				
netructor	Sanit Teawchim			

Evaluation (Rubric)	Ideal Level of Achievement (Very Good)	Standard Level of Achievement (Good)	Unacceptable Level of Achievement (Fail)		
Following and Doing Procedure	Ideal Level of Achievement (Very Good)	Standard Level of Achievement (Good)	Unacceptable Level of Achievement (Fail)		
	Demonstrates very good knowledge of the lab procedures and principles	Demonstrates good knowledge of the lab procedures and principle	Lacks the appropriate knowledge of the lab procedures and principles		
Data Collection	Measurements are both accurate and precise	Measurements are mostly accurate and precise	Measurements are incomplete, inaccurate and imprecise	1	
Report writing	Content is comprehensive, and accurate. Important points are stated clearly with supported	Some contents are not comprehensive or incomplete. Important	Most of the content is incomplete. Important points are addressed and /or inconsistent.	1	
Safety	data. Proper safety precautions and awareness are consistently used	points are addressed, but not well supported. Proper safety precautions and awareness are	Proper safety precautions and awareness are missed	-	
		generally used			
				ł	
M(1) Ability to design, propose and	Relationship with Learnin develop robotio/ mechatron	s Outcomes to systems to solve ap	solfio problems		
M(2) Ability to dealgn, propose and	develop electrical and electr	ronic systems for robo	tice/ mechatronic systems		
M(3) Ability to design, propose and	develop mechanical solution	s/ systems for robotic	/ mechatronic exetems		
Teaching Method				1	
Outline:	Students will study the concept and methodology of Electrical Engineering and Mechanical Engineering. Student will apply their skills, knowledge and learnings through experiment.				
Please Note :	Students are required to ask any questions after sufficient self-learning			ł	
Course Plan Semester 1	Contents and Met	hod of Course	Goale	Related	MCC
Week 1	Introduction of courge.	and Pendulum and	Understanding Introduction	VI-C 1	3
	oscillat	ion	and oscillation	15-0 1	0
Week 2	Simple vibration of	f metal bar (1)	Understanding Simple vibration of metal bar (1)	N.V. 1	ÿ
			Lodontor due Church	VI-C 1	3
Week 3	Simple vibration of meta	l bar/ resonance (2)	Understanding Simple vibration of metal bar/ resonance (2)		
Week 4	Ultrasonic se	msor (1)	Understanding Ultrasonic	VI-C 1	3
Week 5	Ultrasonic se	insor (2)	Understanding Ultrasonic sensor (2)	VI-C 1	3
				VI-C 1	1
Week 6	Resistance an	d Material	Understanding Resistance and Material	VI-0 1	2
			Lindomtonding Internal	VI-C 1 VI-C 1	1 2
Week 7	Internal resistance and Maximum power transfer		resistance and Maximum power transfer		
Wook 8	Writing Berryrts		Understanding Writing		
			Heports		
Week 9	midter	m			
				VI-C 1	1
Week 10	Switch and tou	ich sensors	Understanding Switch and touch sensors	VI-C 1	3
Mark dd	(Sector) Landa		Understanding Digital Logic	VI-C 1 VI-C 1	14 15
1000, 11	Charles Coast	Bourse 17	gate	15-0 1	14
Week 12	Digital Logic	gate(2)	Understanding Digital Logic gate	VI-C 1	15
				VI-C 1	14
Week 13	Digital Logic gate/Adde	r and Substractori	Understanding Digital Logic gate(Adder and Substractor)	VI-C 1	15
Week 14	3D printer lintrod	uce softwarel	Understanding the use of Autodesk Fusion 360	<u>№-8 2</u> №-8 2	4 5
			2- Versions for 3D drawing		
Week 15	3D printeriPrint	ing process)	Understanding file management and printing process		
Week 16	3D printer/Gear	sketch up)	Understanding the use of Autodesk Fusion 360 programs for gear design	<u>K-B</u> 2 K-B 2	4 5
Week 17	3D printer Ev	aluation )	Understanding advantage and disadvantage of 3D printing		
Week 18	Writing Reports				
inten fo	versel E De				
Week 19	Final ø	am			
Week 20	Reflection and R	Reflection and Review reports			
	1		1		Do not
Basic Ability	Performance 50	Quéz	Mutual Deskastions between etudente	Report Porth	<b>Solo Behavior</b> 10
Lecrnical Ability	1			+	