

Numerical Method

Basic Course Information		
Course Number	01005117	Subject Category Computation, IM
Class Format	Lecture	Credit Type and Number of Credits 1
Department	Mechatronics	Student Category Year 5
Period of Study	Semester 1	Classes per Week 1
Required Materials	Book: Calculus and Graphs, no online connection is required	
Instructor	Takashi Yamamoto Multiple Pseudonyms	

Course Objective
The course provides students with introduction and basis of numerical calculation. Students will develop their programs for numerical solutions of differential and integral calculus. In addition, students will implement programs for engineering problems in this course.

Evaluation/Practical	Minimal Level of Achievement (Very Good)	Standard Level of Achievement (Good)	Unacceptable Level of Achievement (Fail)
can implement programs accurately based on algorithms that use various and other basis of numerical calculation.	can implement programs accurately based on algorithms that use various and other basis of numerical calculation.	can implement simple programs based on algorithms that use various and other basis of numerical calculation.	can't implement programs based on algorithms that use various and other basis of numerical calculation.
can explain the solution of nonlinear equations and use it to solve engineering problems.	can explain the solution of nonlinear equations accurately and use it to solve engineering problems.	can explain the solution of nonlinear equations.	can't explain the solution of nonlinear equations.
can explain numerical integration methods and use them to solve engineering problems.	can explain numerical integration methods and use them to solve engineering problems.	can explain numerical integration methods.	can't explain numerical integration methods.
can explain the solution of simultaneous equations based on matrix operations and use it to solve engineering problems.	can explain the solution of simultaneous equations accurately and use it to solve engineering problems.	can explain the solution of simultaneous equations based on matrix operations.	can't explain the solution of simultaneous equations based on matrix operations.
can explain the solution methods for differential equations and use them to solve engineering problems.	can explain the solution methods for ordinary differential equations precisely and use them to solve engineering problems correctly.	can explain the solution methods for ordinary differential equations.	can't explain the solution methods for ordinary differential equations.

Relationship with Learning Outcomes

M4) Ability to design and develop the software for control robots/ mechatronic systems.

Please choose

Teaching Method

Outline Lecture and Practice

Class Format: Lecture, practice and 1 homework assignments.

Please Note : Students require to ask any questions after sufficient self-learning.

Course Plan	Semester 1	Contents and Method of Course	Goals	Related MOC
		Guidance and review of 'Programming 1-5'	Review of Python programming studied in 'Programming 1-5'	V-A 7 101 V-D 1 2 V-D 1 3 V-D 1 4 V-D 1 5 V-D 7 101
		Numerical error / Numerical integration	Explaining what numerical error is in numerical calculation and implementing numerical integration algorithms (trapezoidal method)	V-A 7 102 V-D 7 102 V-D 7 202 V-D 7 302 V-D 7 402
		Root-finding of non-linear equation (1)	Explaining what bisectional method and Regula-Falsi method to obtain roots of equations (python code)	V-A 7 103 V-D 7 103 V-D 7 203 V-D 7 303
		Root-finding of non-linear equation (2)	Explaining the algorithms of the Newton-Raphson method and implementing python code	V-A 7 104 V-D 7 104 V-D 7 204 V-D 7 304
		Root-finding of non-linear equation(3)	Solving engineering problems using root-finding methods and explaining the difference among 3 different finding methods.	V-A 7 105 V-D 7 105 V-D 7 205 V-D 7 305
		Numerical methods for systems of linear algebraic equation: iterative method (1)	Explaining the algorithm of the Gauss elimination method and implementing Python code	V-A 7 106 V-D 7 106 V-D 7 206 V-D 7 306
		Preparing mid-term examination		
		Mid-term examination		
		Numerical methods for systems of linear algebraic equation: iterative method (2)	Explaining the algorithm of the LU decomposition method and implementing Python code	V-A 7 107 V-D 7 107 V-D 7 207 V-D 7 307
		Numerical methods for systems of linear algebraic equation: iterative method (3)	Explaining the algorithm of pivoting in Gauss elimination and LU decomposition and implementing Python code	V-A 7 108 V-D 7 108 V-D 7 208 V-D 7 308
		Numerical methods for systems of linear algebraic equation: iterative method (4)	Explaining the algorithm of Cholesky decomposition (tri-diagonal coefficient matrix) and implementing Python code	V-A 7 109 V-D 7 109 V-D 7 209 V-D 7 309
		Numerical methods for systems of linear algebraic equation: Direct method	Explaining the algorithms of Gauss-Seidel and SOR methods and implementing Python code	V-A 7 110 V-D 7 110 V-D 7 210 V-D 7 310
		Numerical interpolation (1)	Explaining the algorithm of Lagrange's interpolation method and implementing Python code	V-A 7 111 V-D 7 111 V-D 7 211 V-D 7 311
		Numerical interpolation (2)	Explaining the algorithm of Lagrange's interpolation method and implementing Python code	V-A 7 112 V-D 7 112 V-D 7 212 V-D 7 312
		Curve fitting	Explaining the algorithm of least-square fitting and implementing Python code	V-A 7 113 V-D 7 113 V-D 7 213 V-D 7 313
		Numerical differentiation	Explaining the algorithms of finite differential approaches and implementing Python code	V-A 7 114 V-D 7 114 V-D 7 214 V-D 7 314
		Partial differential equation	Explaining the algorithms of partial differential equations using finite differential approaches and implementing Python code	V-A 7 115 V-D 7 115 V-D 7 215 V-D 7 315
		Preparing final examination		
		Final examination		
		Return exam papers and feedback	Review and summarize learning during this course.	

	Submission	Quiz	Manual Examinations between students	Report	Partials	Other
Basic Ability	10	15		15		
Technical Ability	20					
Character/Ethics Ability						

Do not